

Data sheet

FxiS / FxeS







Туре		F0iS	F1iS	F1iS	F2iS	F2iS
Accuracy class standard	%			0,05		
Rated torque Mn	Nm	50 100 200 500 1000	200 500 1000 1500	2000 2500 3000	2500 5000 7000	10000 15000 20000

Torque measuring system						
Technology	-			Rotating		
Rated torque Mn <u># 2</u>	Nm	50 100 200 500 1000	200 500 1000 1500	2000 2500 3000	2500 5000 7000	10000 15000 20000
Rated torque second channel (Minimum), optional #3	Nm	20 20 40 100 200	40 100 200 300	400 500 600	500 1000 2000	2000 3000 4000
Accuracy class optional	%			0,03		
Outer diameter of rotor # 1	mm	94	150	150	230	230
Lengths (Rotor, without centering)	mm	74	80	80	107	107
Pitch circle diameter <u># 8</u>	mm	75	130	130	196	196
Outputs	-	Frequency, Voltage, Current, CAN bus, Alert				rt
Speed measuring system						
Speed detection (integrated)	-	without	inductive	inductive	inductive	inductive
Speed detection (optional)	-	inductive / optical	magn.	magn.	magn.	magn.
Maximum Speed without optional speed measuring system	rpm	20000	20000	20000	15000	15000
Optional increased speed	rpm	25000	25000	25000	17000	17000
Maximum speed with magnetic speed encoder	rpm	N/A	9000	9000	6500	6500
Maximum speed with optical speed encoder	rpm	20000	N/A	N/A	N/A	N/A
Maximum speed with optical speed encoder Maximum speed with inductive speed encoder	rpm rpm	20000 20000	N/A 20000	N/A 20000	N/A 12500	N/A 12500
Maximum speed with inductive speed encoder						
Maximum speed with inductive speed encoder Torque Accuracy (related to rated torque)	rpm			20000		
Maximum speed with inductive speed encoder Torque Accuracy (related to rated torque) Frequency output / CAN	rpm %			20000 ≤±0,05		



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Accuracy class standard	%			0,05			
Rated torque Mn	Nm	50 100 200 500 1000	200 500 1000 1500	2000 2500 3000	2500 5000 7000	10000 15000 20000	
Linearity deviation including hysteresis related to nomina	ıl value						
Frequency / CAN, 0% 30% of Mn	%			≤±0,01			
Frequency / CAN, 30% 60% of Mn	%			≤±0,02			
Frequency / CAN, 60% 100% of Mn	%			≤±0,03			
Voltage output	%			≤±0,05			
Current output	%			±0,05			
Rel. standard deviation of the reproducibility according to DIN 1319, by reference to variation of the output signal							
Frequency output / CAN	%	≤±0,03					
Voltage output	%	≤±0,05					
Current output	%	≤±0,05					
Test signal	-	see test report					
Temperature Influence per 10K in the nominal temperatu	re range on the	output signal ı	related to the a	actual value of	signal span		
Frequency output / CAN	%			≤±0,05			
Voltage output	%			≤±0,1			
Current output	%			≤±0,1			
Temperature influence per 10K in the nominal temperatu	re range on the	zero signal, re	lated to the no	ominal sensitiv	ity		
Frequency output / CAN	%			≤±0,05			
Voltage output	%			≤±0,1			
Current output	%			≤±0,1			
Long-term drift over 48h at reference temperature							
Voltage output	mV			<1			
Current output	μΑ			<0,8			
Temperature range							
Nominal temperature range rotor/stator	°C		(0+80 / 0+70)		
Operating temperature range rotor/stator	°C		-20)+85 / -20+	70		
Storage temperature range rotor/stator	°C	-30+85					



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Rated torque Mn	Nm	50 100 200 500 1000	200 500 1000 1500	2000 2500 3000	2500 5000 7000	10000 15000 20000

Nominal sensitivity (range between zero torque and i	rated torque)	
Frequency output	kHz	20
Voltage output	V	5 / 10 / 2,5 / 5
Current output	mA	8 / 10
Output signal at zero torque		
Frequency output	kHz	60
Voltage output	V	0 / 0 / 2,5 / 5
Current output	mA	12 / 10
Nominal output signal		
Frequency output at positive nominal value	kHz	80
Frequency output at negative nominal value	kHz	40
Voltage output at positive nominal value	V	5/10/5/10
Voltage output at negative nominal value	V	-5 / -10 / 0 / 0
Current output at positive nominal value	mA	20
Current output at negative nominal value	mA	4 / 0
Max. modulation range		
Frequency output	kHz	3090
Voltage output	V	-10,5+10,5
Current output	mA	024
Group delay time		
Frequency output	μs	10
Voltage output	μs	3000
CAN	μs	1000



	F0iS	F1iS	F1iS	F2iS	F2iS
%			0,05		
Nm	50 100 200 500 1000	200 500 1000 1500	2000 2500 3000	2500 5000 7000	10000 15000 20000
	Ind	uctive (integra	ted track at ro	tor)	
ppr.	30	60	60	120	120
kHz			25		
rpm			>0		
Ma	agneto resistive	e (2 tracks ap	prox. 90 degre	ee phase shifte	ed)
ppr.	N/A	1000	1000	1448	1448
kHz	N/A	250	250	250	250
rpm	N/A	>0	>0	>0	>0
mm	N/A	0,7	0,7	0,7	0,7
mm	N/A	0,11,0	0,11,0	0,11,0	0,11,0
mm	N/A	2	2	4	4
mm	N/A	±0,5	±0,5	±0,5	±0,5
		Opt	tical		
ppr.	360 / 400 / 240	N/A	N/A	N/A	N/A
kHz	250 (RS422)	N/A	N/A	N/A	N/A
rpm	>0	N/A	N/A	N/A	N/A
mm	1,5	N/A	N/A	N/A	N/A
mm	1,41,6	N/A	N/A	N/A	N/A
	ppr. kHz rpm mm mm mm ppr. kHz rpm mm mm mm	% SO	% Nm 50 100 500 500 1000 200 500 1500 Inductive (integral ppr. 30 60 kHz N/A 1000 kHz N/A 250 rpm N/A 90 mm N/A 0,7 mm N/A 0,11,0 mm N/A 2 mm N/A 2 ppr. 360 / 400 / 240 N/A N/A 2 kHz 250 (RS422) N/A rpm >0 N/A mm N/A	% 0,05 Nm 50 100 500 500 1000 200 2500 3000 500 1000 1500 2500 3000 Inductive (integrated track at room ppr. ppr. 30 60 60 kHz 25 70 Magneto resistive (2 tracks approx. 90 degree ppr. ppr. N/A 1000 1000 kHz N/A 250 250 rpm N/A 0,7 0,7 mm N/A 0,11,0 0,11,0 mm N/A 2 2 mm N/A 20,5 20,5 Optical ppr. 360 / 400 / 240 N/A N/A kHz 250 (RS422) N/A N/A rpm >0 N/A N/A mm 1,5 N/A N/A	% 0,05 Nm 50 100 200 500 1000 200 500 1000 2500 5000 3000 2500 5000 7000 bpr. 30 60 60 120 kHz 25 1000 1000 1448 kHz 25 1000 1000 1448 kHz N/A 1000 1000 1448 kHz N/A 250 250 250 rpm N/A 0,7 0,7 0,7 mm N/A 0,11,0 0,11,0 0,11,0 mm N/A 2 2 4 mm N/A ±0,5 ±0,5 ppr. 360 / 400 / 240 N/A N/A N/A kHz (RS422) (RS422) N/A N/A N/A rpm >0 N/A N/A N/A mm 1,5 N/A N/A N/A N/A

Tolerance to nominal displacement (rotor - stator)

+0,5/-0,3

mm

N/A

N/A

N/A

N/A



Bending limit torque

Туре		F0iS	F1iS	F1iS	F2iS	F2iS
Accuracy class standard	%			0,05		
Rated torque Mn	Nm	50 100 200 500 1000	200 500 1000 1500	2000 2500 3000	2500 5000 7000	10000 15000 20000
Load limits # 7						
Limit torque, related to Mn	%			500		
Breaking torque approx., related to Mn	%			1000		
Axial limit force	kN	9 13 19 40 81	11 15 28 34	40 45 50	112 159 213	213 296 332
Lateral limit force	N	245 480 950 2680 6790	770 1230 3520 4920	6280 7620 8790	6701 11876 20543	20543 41963 55227
Bending limit torque	Nm	14 27 53	41 66	336 408	457 810	1402 2863

Nm

53

150

379

408

470

188

263

810

1402

2863

3769



recillicat Data						
Туре		F0iS	F1iS	F1iS	F2iS	F2iS
Accuracy class standard	%			0,05		
Rated torque Mn	Nm	50 100 200 500 1000	200 500 1000 1500	2000 2500 3000	2500 5000 7000	10000 15000 20000
Mechanical values						
Torsional stiffness	kNm/rad	17 40 92 275 630	93 160 490 675	880 1065 1230	897 1701 3244	3244 8769 12630
Angle of twist at Mn	o	0,17 0,14 0,12 0,1 0,09	0,12 0,18 0,12 0,13	0,13 0,13 0,14	0,16 0,17 0,12	0,18 0,1 0,09
Axial stiffness	kN/mm			N/A		
Radial stiffness	kN/mm			N/A		
Bending stiffness	kN/°			N/A		
Deflection at axial limit force	mm			N/A		
Additional radial deviation at lateral limit force	mm			N/A		
Parallel deviation at bending limit torque	mm			N/A		
Inherent frequency	Hz	600 900 1300 2300 3300	590 770 1350 1600	1810 2000 2160	600 850 1200	1200 1800 2100
Balance quality-level to DIN ISO 1949	-			G2.5		
Inertia of rotor	kgm²	0,0013 0,0013 0,0014 0,0014 0,0015	0,0112 0,0113 0,0113 0,0113	0,0114 0,0114 0,0115	0,0788 0,0792 0,0799	0,0799 0,0827 0,0848



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Accuracy class standard	%			0,05		
Rated torque Mn	Nm	50 100 200 500 1000	200 500 1000 1500	2000 2500 3000	2500 5000 7000	10000 15000 20000
Weight						
Weight approx.		1.00				
Rotor <u># 6</u>	kg	1,23 1,28 1,35 1,5 1,7	4,1 4,1 4,1 4,2	4,3 4,3 4,4	13,5 13,6 14,1	14,1 15,2 16
Stator (without speed encoder) # 6	kg	2,1	2,1	2,1	3	3
Mounting distances (without optional speed detection)						
Nominal radial displacement (rotor - stator)	mm	2,1	2,5	2,5	2,5	2,5
Tolerance to nominal radial displacement (rotor - stator)	mm	<±2,1	<±2,5	<±2,5	<±2,5	<±2,5
Nominal axial displacement rotor - stator # 4	mm	4	2	2	4	4
Tolerance to nominal axial displacement rotor - stator	mm	+0,5/-0,3	±0,5	±0,5	±0,5	±0,5
Flatness and concentricity tolerances rotor						
Circular run-out-axial tolerance # 5	mm			0,01		
Circular run-out-radial tolerance # 5	mm			0,01		
Power supply						
Nominal supply	V (DC)			24		
Max. current consumption in measuring mode	Α			<0,7		
Max. current consumption in start-up mode	Α			<2		
Nominal power consumption	W			<17		
Load resistance						
Frequency output	-			RS422		
Voltage output	kOhm			≥5		
Dynamic						
Frequency output	kHz			≤7		
Voltage output Fx	kHz			1		
Current output Fx	kHz			1		
CAN Output conversation rate	1/s			≤1000		

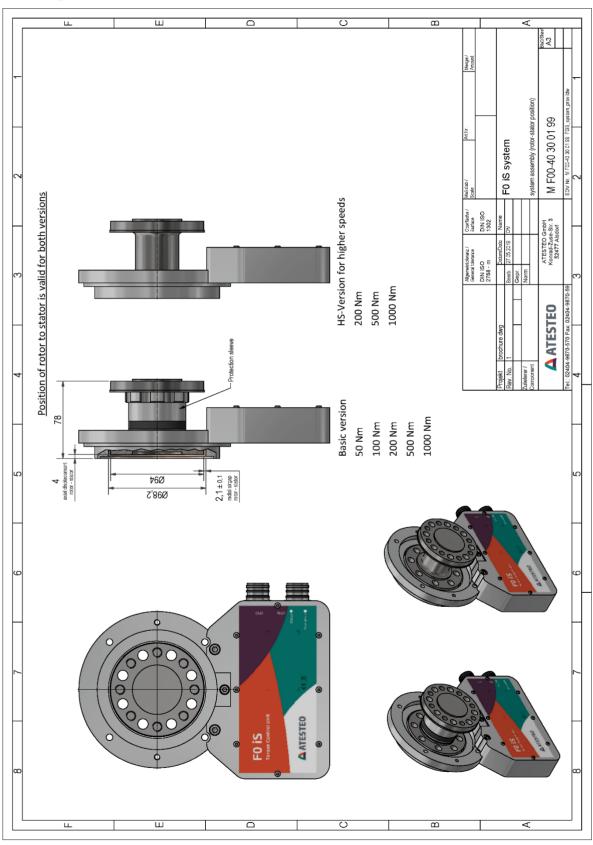


Remarks and information

Link no.	Торіс	Remark
#1	Detail in the drawings	Value can vary by optional components. Please find details to this attribute in the integrated drawings.
#2	Nominal torque	Based on customer requests, the measurement systems can optionally be optimized for not listed nominal torque values (intermediate ranges possible).
" 0	2	The written second torque range is the smallest possible complying with the given accuracy class. Greater second torque ranges can be chosen on demand.
#3	Second torque range	It must be noticed that the mechanical data and load limts will vary for systems with a second measurement range.
#4	Reference planes	Please check the drawings for information about the reference planes of this attribute.
#5	Flatness and concentricity tolerances	The parameters of "Flatness and concentricity tolerances rotor" are manufacturing tolerances.
#6	Weights	Weights are related to components without speed detection system.
#7	Load limits	The given values are only valid if no other load occurs at the same time. If the loads in sum are 100%, the max. error will be 0.3% of the nominal torque.
#8	Pitch circle diameter	The pitch circle diameter is identically at input and output side for most systems. More information is given in the drawings of a product.

F0-F2 (iS)

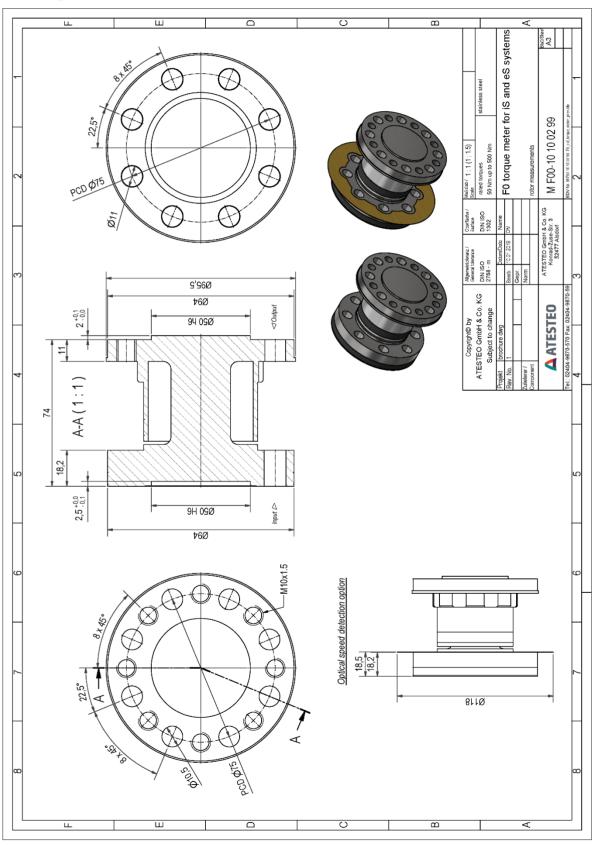
Drawing



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F0iS F0-F2 (iS)

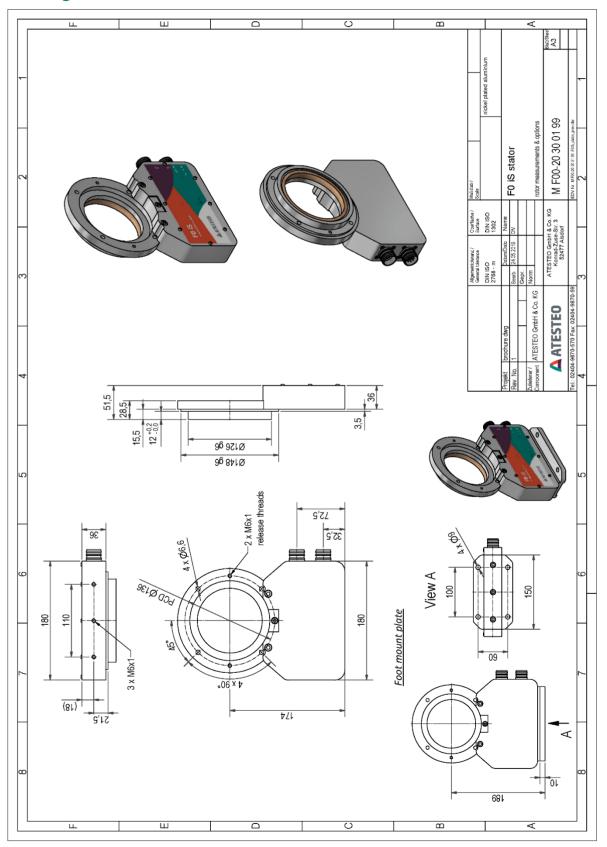
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F0iS F0-F2 (iS)

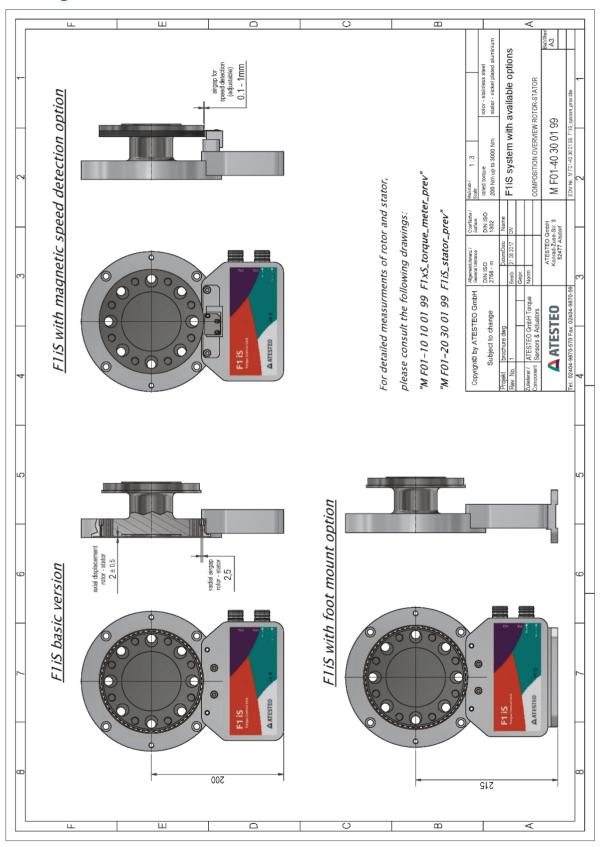
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F1iS F0-F2 (iS)

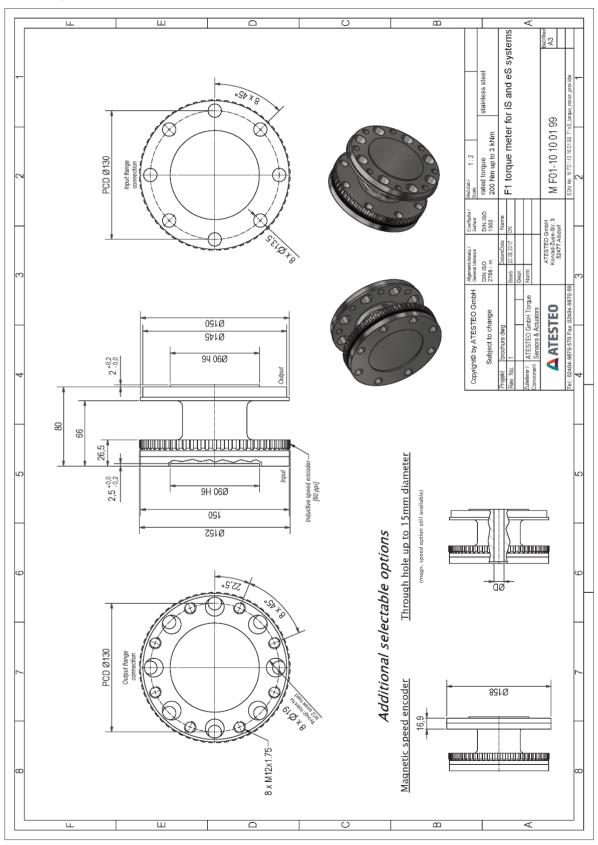
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F1iS F0-F2 (iS)

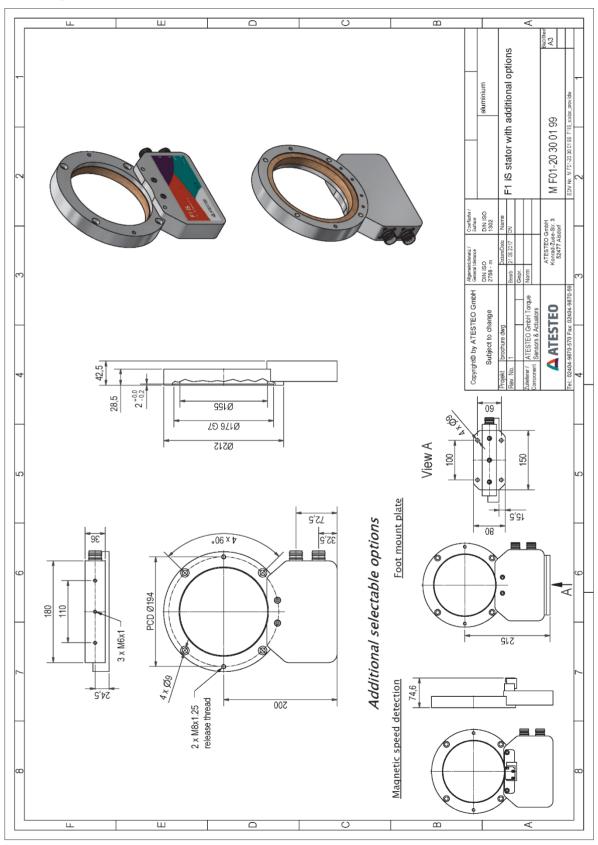
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F1iS F0-F2 (iS)

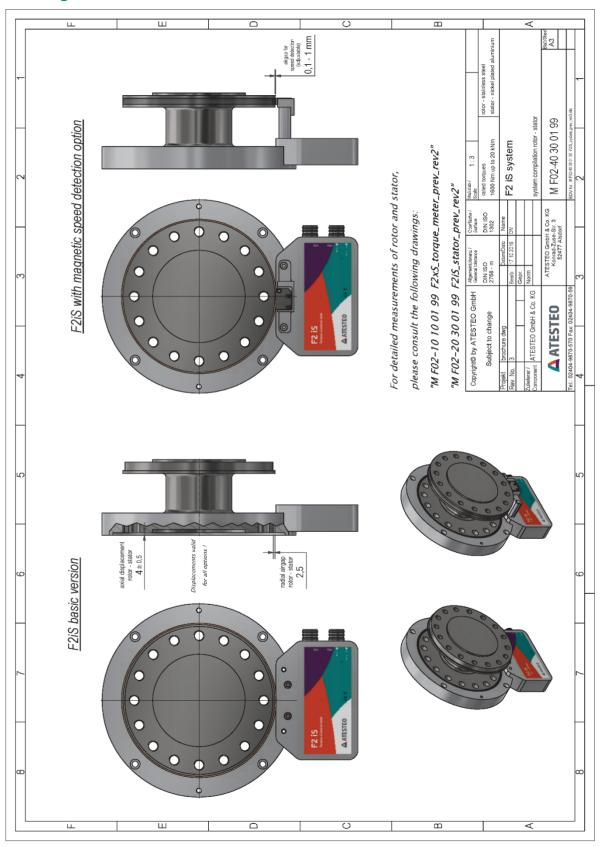
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F2iS F0-F2 (iS)

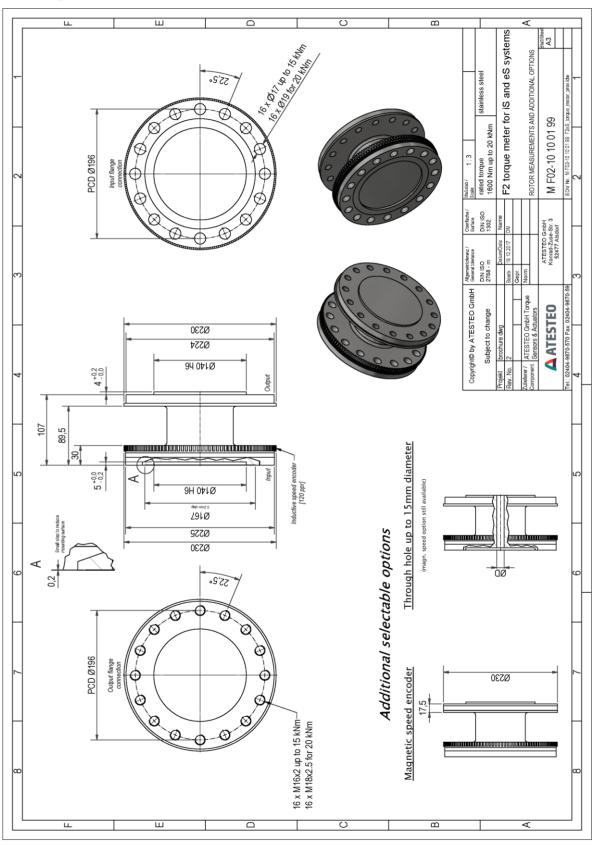
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F2iS F0-F2 (iS)

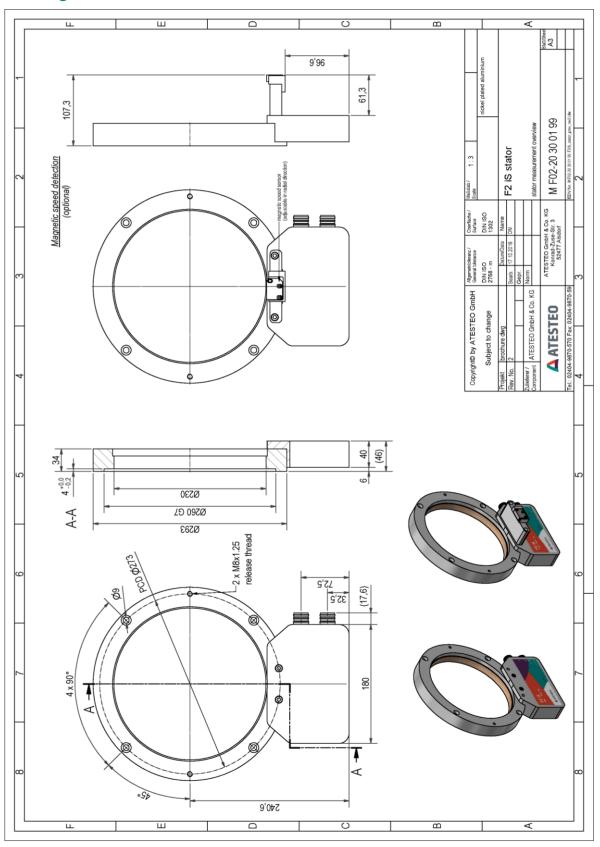
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F2iS F0-F2 (iS)

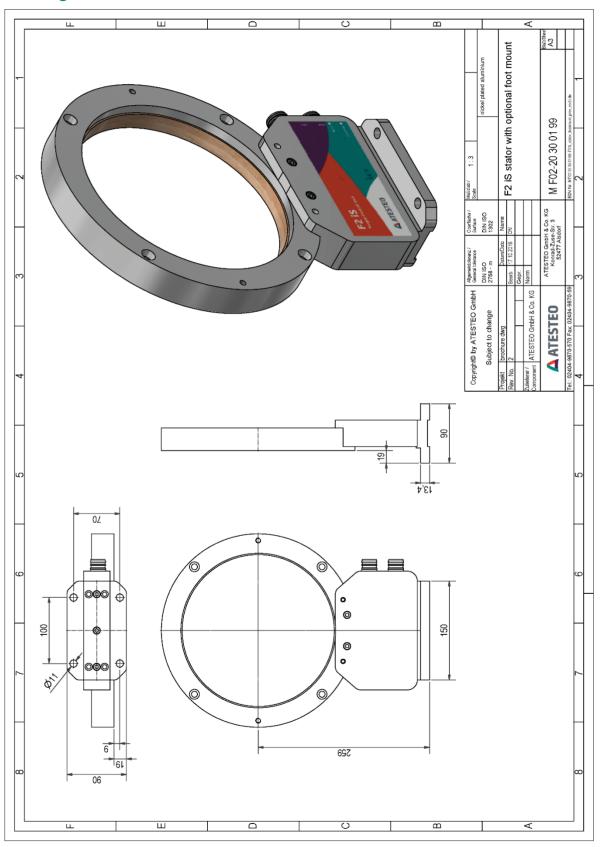
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F2iS F0-F2 (iS)

Drawing



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